



CATT

CENTER FOR ADVANCED
TRANSPORTATION TECHNOLOGY



MARYLAND
TRANSPORTATION
INSTITUTE

UMD CATT Connected Autonomous Vehicle (CAV) Research

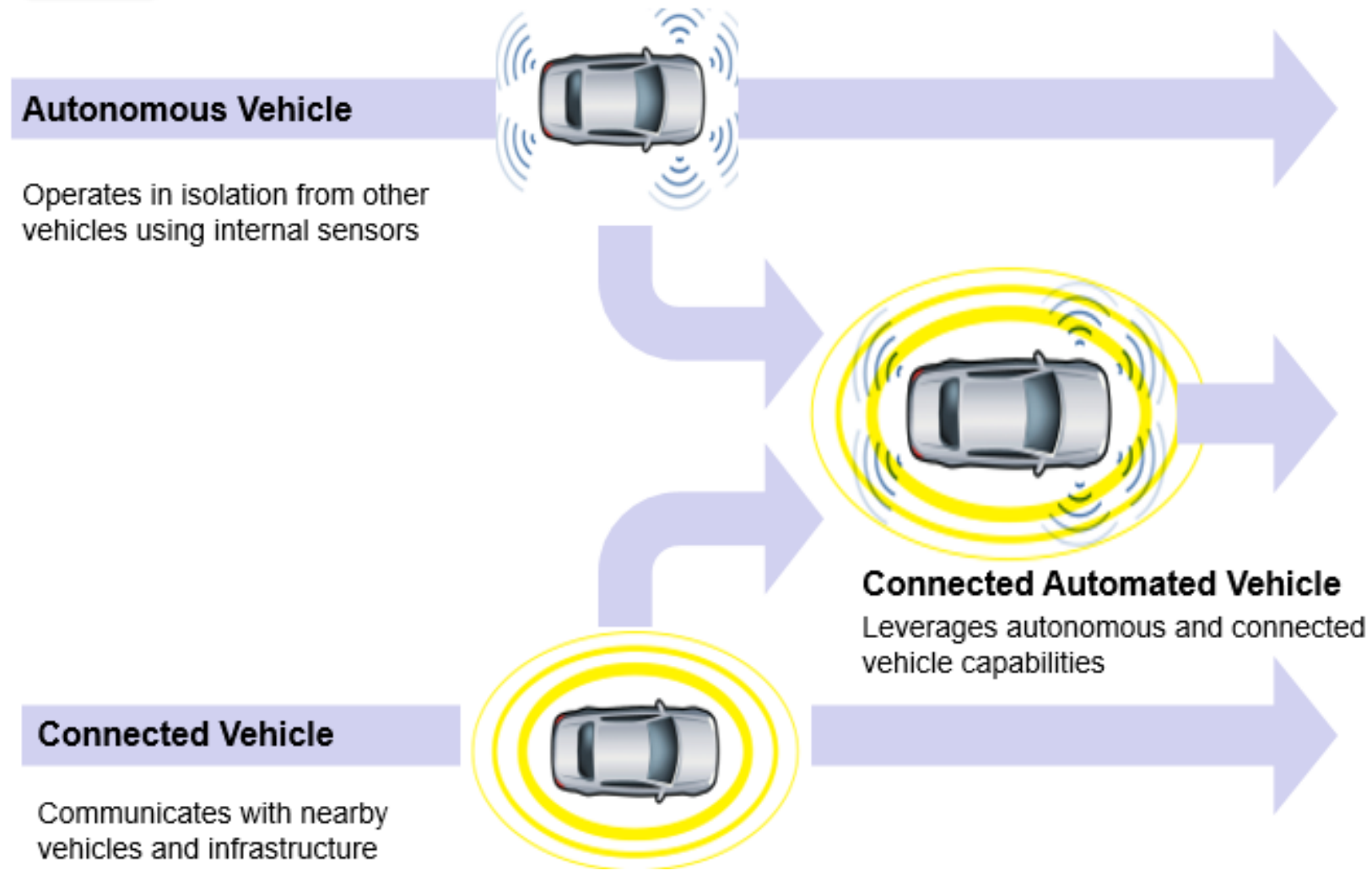
Smart Cities Symposium

September 2019



A. JAMES CLARK
SCHOOL OF ENGINEERING

Connected Automated Vehicles



SAE Levels of Automation

SOCIETY OF AUTOMOTIVE ENGINEERS (SAE) AUTOMATION LEVELS

Full Automation



0

No Automation

Zero autonomy; the driver performs all driving tasks.

1

Driver Assistance

Vehicle is controlled by the driver, but some driving assist features may be included in the vehicle design.

2

Partial Automation

Vehicle has combined automated functions, like acceleration and steering, but the driver must remain engaged with the driving task and monitor the environment at all times.

3

Conditional Automation

Driver is a necessity, but is not required to monitor the environment. The driver must be ready to take control of the vehicle at all times with notice.

4

High Automation

The vehicle is capable of performing all driving functions under certain conditions. The driver may have the option to control the vehicle.

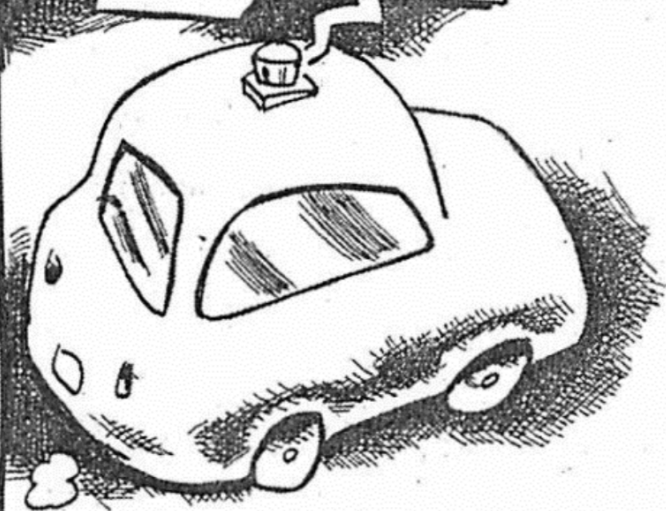
5

Full Automation

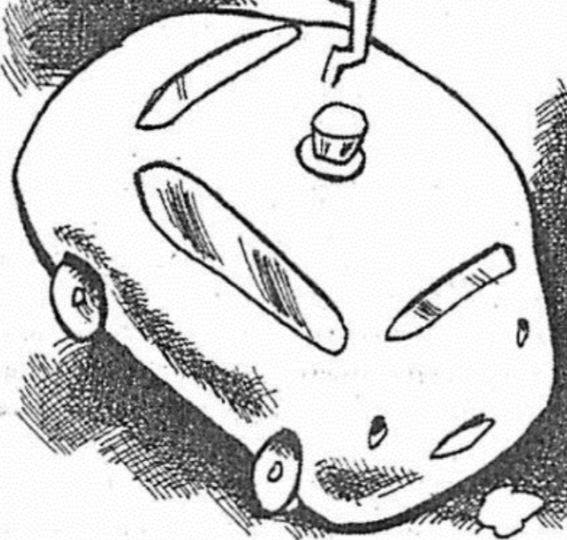
The vehicle is capable of performing all driving functions under all conditions. The driver may have the option to control the vehicle.

Source: <https://www.nhtsa.gov/technology-innovation/automated-vehicles-safety>

... I AM APPROACHING
FROM YOUR LEFT AND
AM MAKING PRECAUTIONARY
ADJUSTMENTS...



ACKNOWLEDGED.
NOT A PROBLEM
UNLESS THE SLAB
OF MEAT IN HERE
INTERFERES...



Intermediate stage en route to driverless cars.

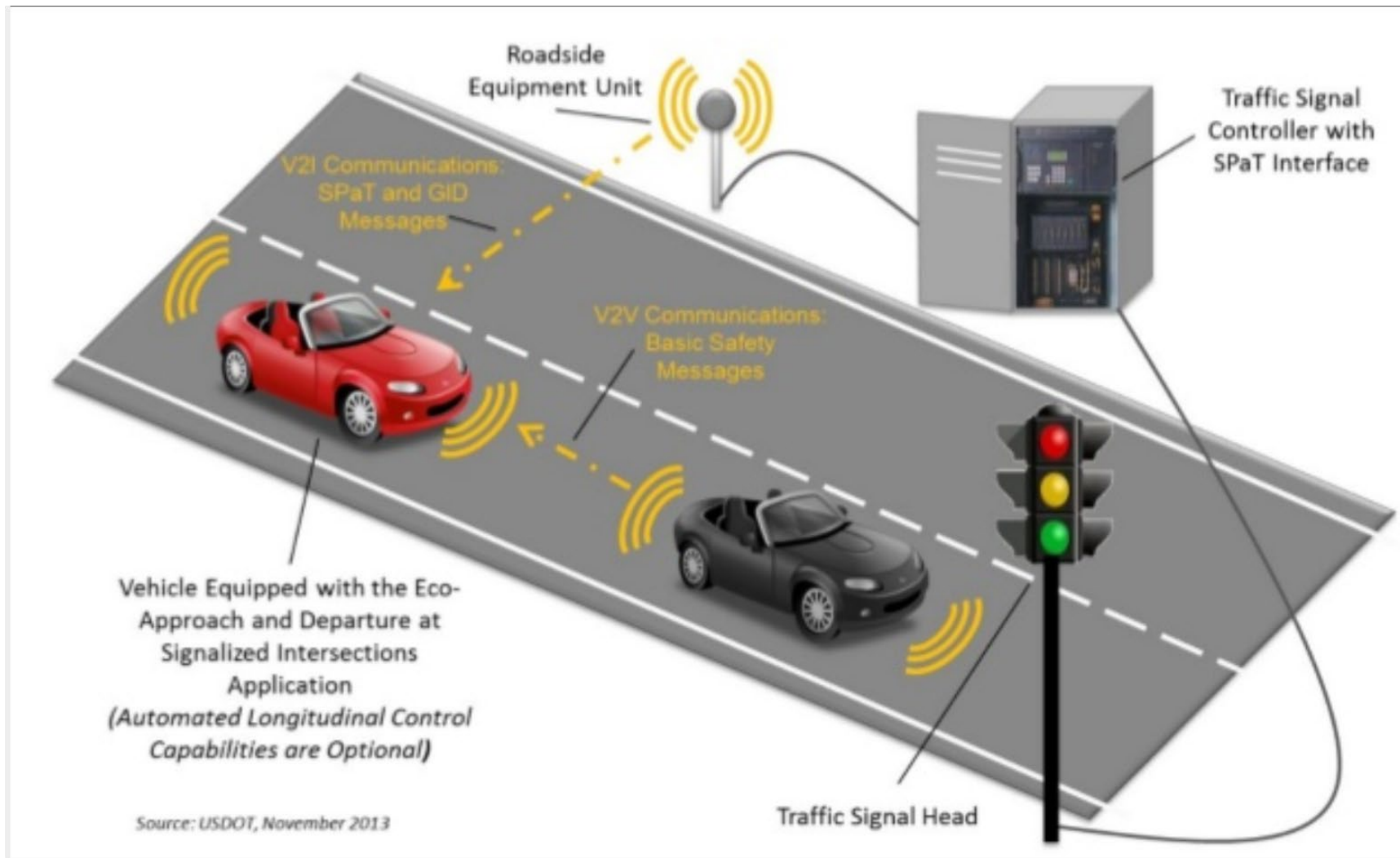
TOLIS

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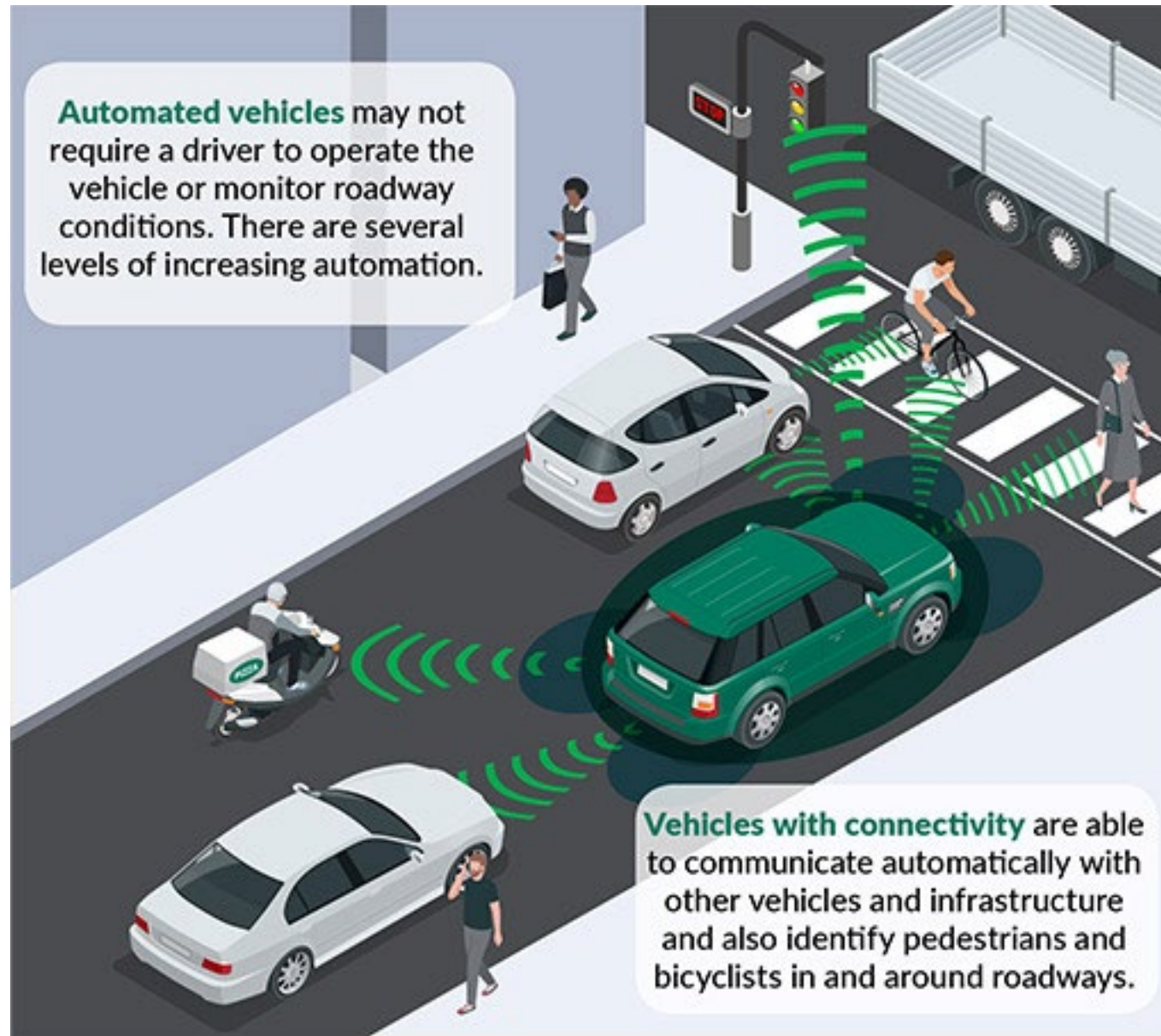
IS SLAB-WATCHING
DISTRACTED DRIVING? —



Arterial Use Case



Arterial Use Case



UMD CATT CAV Research Areas

Pedestrian/Bike/Other Detection

- Intersection Object Detection
- Intersection Object Tracking
- Work Zone Identification
- Dilemma Zone Identification
- DSRC/Cellular Safety Message (BSM/PSM) Transmission

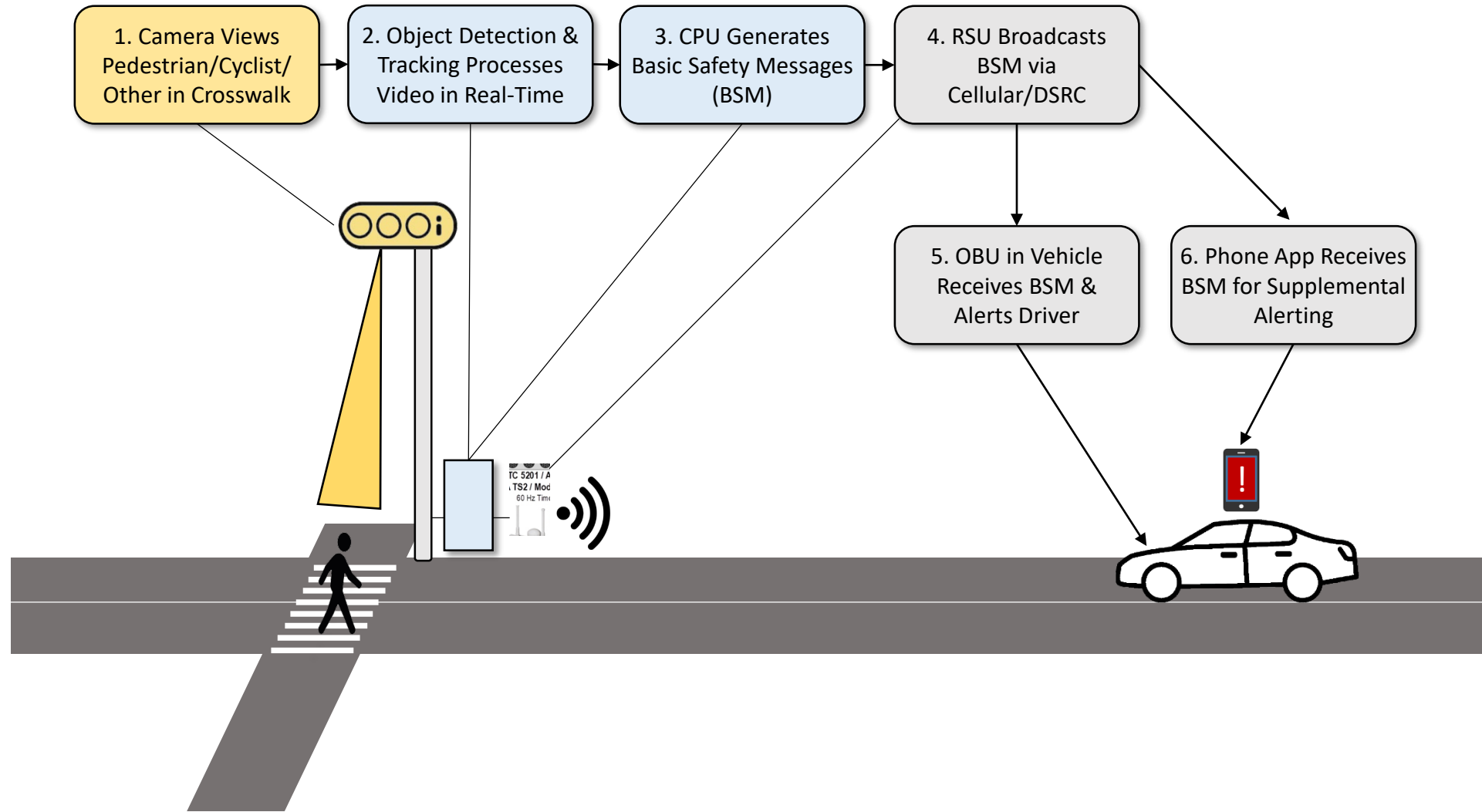
Vehicle Operation Guidance

- DSRC/Cellular Safety Message (BSM/PSM) Receipt
- Work zone messaging (Speed, Merging, etc.)
- Variable speed limits

Route 1 & Knox Road



Object Detection & Tracking and BSM Alert Generation & Receipt



Lab

RSU (infrastructure side) and OBUs (vehicle side)
Camera, Comms, PC, etc., & Cobalt Controller (loaner)

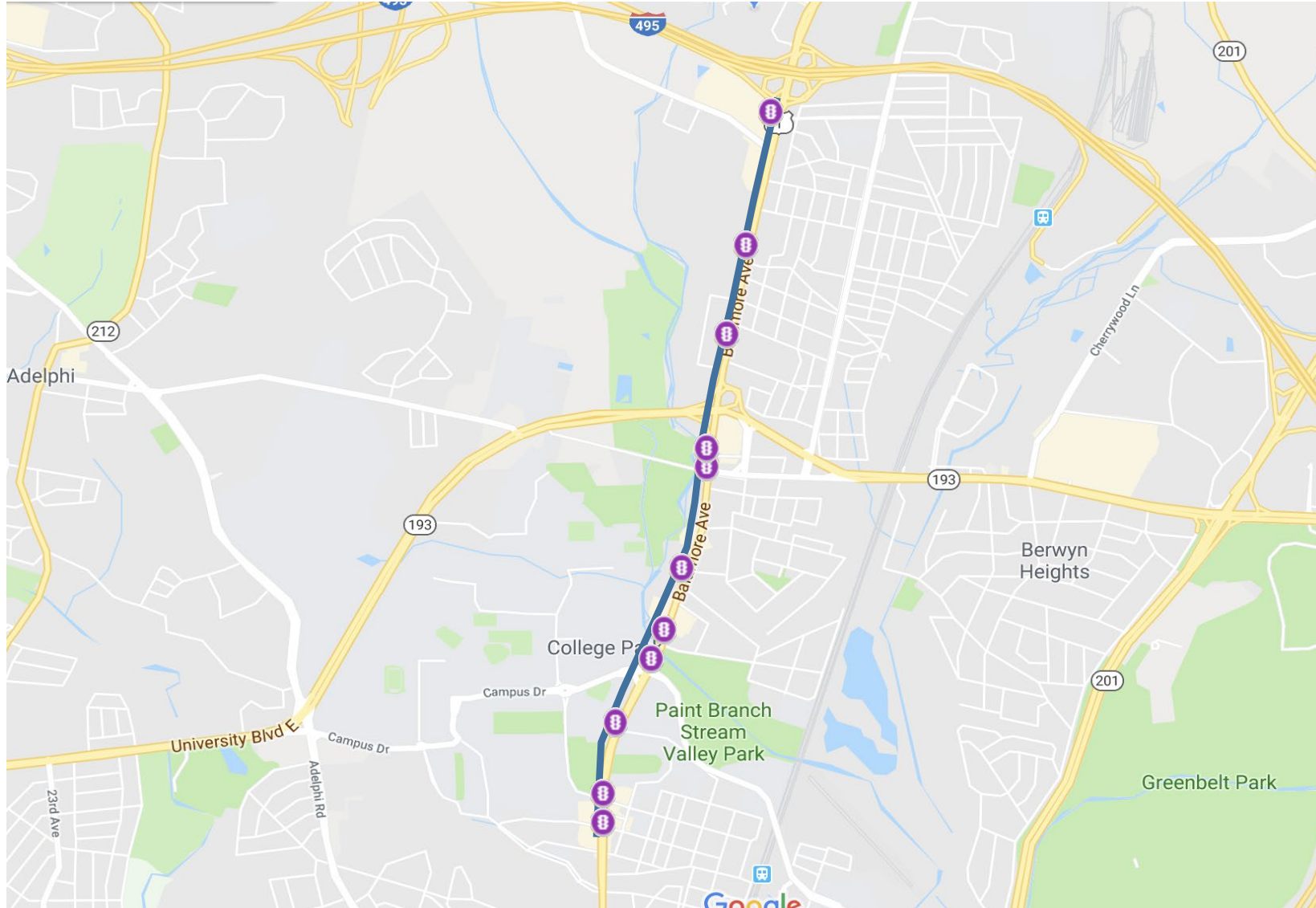


Kapsch sniffer (Danlaw OBU + eTrans Insight app)
Used to independently verify the type, content, and quality of messages that are being broadcast

Current Work

- Continue Prototyping of Object/Pedestrian Detection Algorithms
- Continue Development of BSM/PSM Broadcast and Receipt Messaging, Including Leveraging DSRC & Cellular Technologies
- Prototype In-Vehicle and On-Infrastructure Alerting Solutions, Including Phone App Development
- Test Integration with Third-Party Commercial Technologies
- Coordinate Prototyping and Testing with State and Local Jurisdictions on and Around UMD College Park Campus – Includes Access to Control Signal Cabinet (Cobalt Preferred) & Iteris Camera Mount

Possible Smart Cities Route 1 Demo Corridor



Why a Demo Corridor?



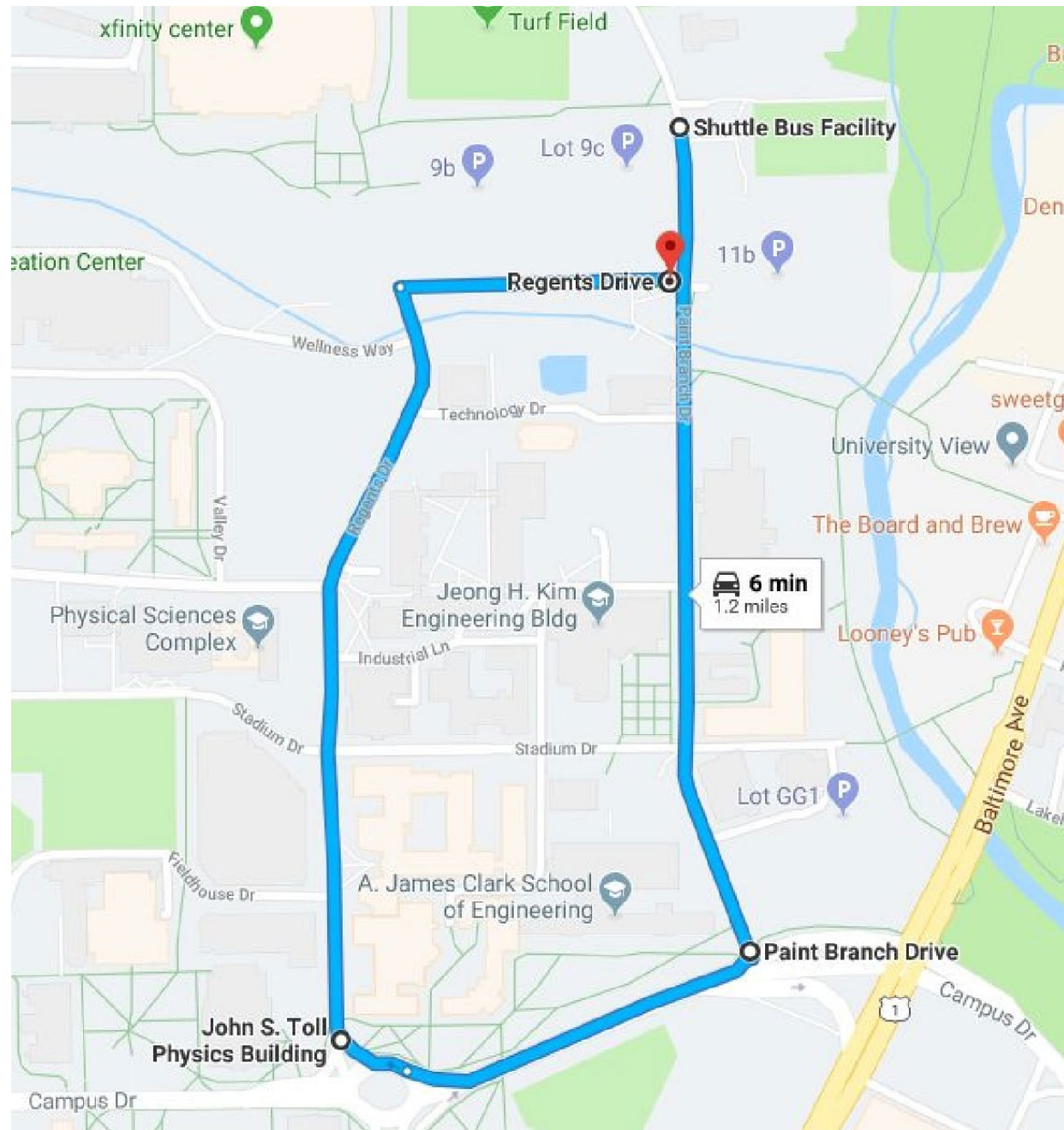
The main goals of the testbed are to:

- Facilitate the development and implementation of advanced technologies
- Foster collaboration with industry wishing to test and further enhance their own technologies
- Improve mobility and safety on campus and around Gainesville
- Quantify the minimum criteria for operators to safely engage with automated vehicles
- To become a model nationally and internationally for the use of advanced technologies to enhance transportation.

Other related CAV Pilot - Olli

- Level 4 Automated Transit Vehicle
- Local Motors (MD Company in National Harbor)
- 3 month pilot funded by Clark School & MTI
- Currently negotiating agreement





xfinity center

Turf Field

Shuttle Bus Facility

9b P

Lot 9c P

11b P

Regents Drive

ation Center

Wellness Way

Technology Dr

Valley Dr

Physical Sciences Complex

Jeong H. Kim Engineering Bldg

Industrial Ln

Stadium Dr

Stadium Dr

Fieldhouse Dr

A. James Clark School of Engineering

Lot GG1 P

Paint Branch Drive

John S. Toll Physics Building

Campus Dr

6 min
1.2 miles

Baltimore Ave

1

Campus Dr

sweetg

University View

The Board and Brew

Looney's Pub

Lakel

Questions?